

# Spectral Clustering

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# Spectral Clustering?

- ▶ Spectral methods
  - ▶ Methods using eigenvectors of some matrices
  - ▶ Involve eigen-decomposition (or spectral decomposition)
- ▶ Spectral clustering methods: Algorithms that cluster data points using eigenvectors of matrices derived from the data
- ▶ Closely related to spectral graph partitioning
- ▶ Pairwise (similarity-based) clustering methods
  - ▶ Standard statistical clustering methods assume a probabilistic model that generates the observed data points
  - ▶ Pairwise clustering methods define a similarity function between pairs of data points and then formulates a criterion that the clustering must optimize

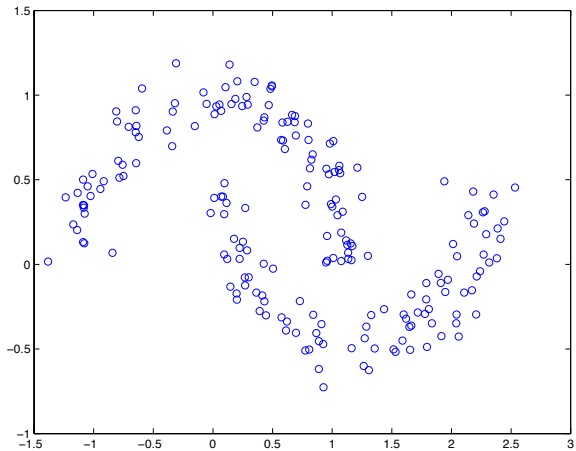
# Spectral Clustering Algorithm: Bipartitioning

1. Construct **affinity matrix**

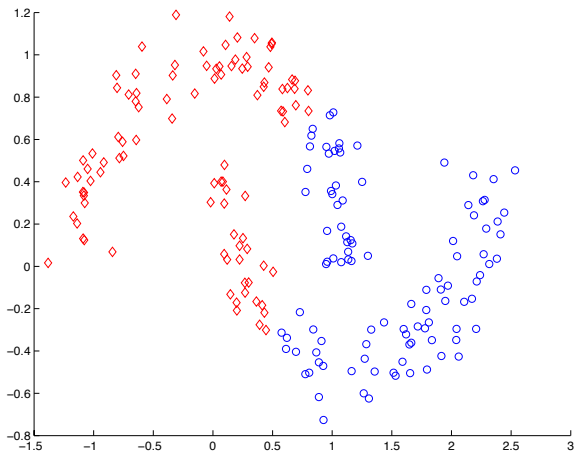
$$W_{ij} = \begin{cases} \exp\{-\beta\|v_i - v_j\|^2\} & \text{if } i \neq j \\ 0 & \text{if } i = j \end{cases}$$

2. Calculate the **graph Laplacian**  $L = D - W$  where  $D = \text{diag}\{d_1, \dots, d_n\}$  and  $d_i = \sum_j W_{ij}$  is the **degree** of node  $v_i$ .
3. Compute the **second smallest eigenvector** of the graph Laplacian (denoted by  $u = [u_1 \cdots u_n]^T$ , **Fiedler vector**)
4. Partition  $u_i$ 's by a pre-specified threshold value and assign data points  $v_i$  to cluster.

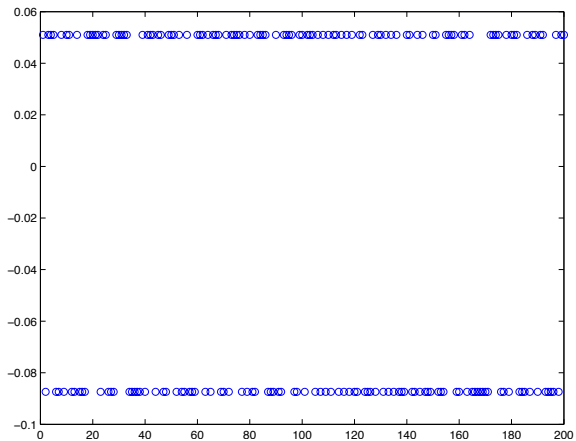
# Two Moons Data



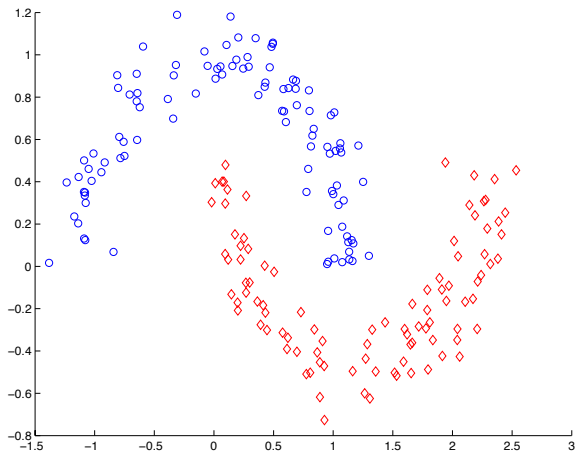
## Two Moons Data: $k$ -Means



# Two Moons Data: Fiedler Vector



# Two Moons Data: Spectral Clustering



# Graphs

- ▶ Consider a connected graph  $\mathcal{G}(\mathcal{V}, \mathcal{E})$  where  $\mathcal{V} = \{v_1, \dots, v_n\}$  and  $\mathcal{E}$  denote a set of **vertices** and a set of **edges**, respectively, with pairwise similarity values being assigned as edge weights.
- ▶ **Adjacency matrix** (**similarity, proximity, affinity matrix**):  
 $W = [W_{ij}] \in \mathbb{R}^{n \times n}$ .
- ▶ **Degree** of nodes:  $d_i = \sum_j W_{ij}$ .
- ▶ **Volume**:  $\text{vol}(\mathcal{S}_1) = d_{\mathcal{S}_1} = \sum_{i \in \mathcal{S}_1} d_i$ .



# Neighborhood Graphs

Gaussian similarity function is given by

$$w(v_i, v_j) = W_{ij} = \exp \left\{ -\frac{\|v_i - v_j\|^2}{2\sigma^2} \right\}.$$

- ▶  $\epsilon$ -neighborhood graph
- ▶  $k$ -nearest neighbor graph

# Graph Laplacian

(Unnormalized) graph Laplacian is defined as  $L = D - W$ .

1. For every vector  $x \in \mathbb{R}^n$ , we have

$$x^T Lx = \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n W_{ij} (x_i - x_j)^2 \geq 0. \quad (\text{positive semidefinite})$$

2. The smallest eigenvalue of  $L$  is 0 and the corresponding eigenvector is  $\mathbf{1} = [1 \cdots 1]^T$ , since  $D\mathbf{1} = W\mathbf{1}$ , i.e.,  $L\mathbf{1} = 0$ .
3.  $L$  has  $n$  nonnegative eigenvalues,  $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n = 0$ .

$$\begin{aligned}x^{\top} L x &= x^{\top} D x - x^{\top} W x \\&= \sum_{i=1}^n d_i x_i^2 - \sum_{i=1}^n \sum_{j=1}^n W_{ij} x_i x_j \\&= \frac{1}{2} \left( \sum_i d_i x_i^2 - 2 \sum_i \sum_j W_{ij} x_i x_j + \sum_j d_j x_j^2 \right) \\&= \frac{1}{2} \sum_i \sum_j W_{ij} (x_i - x_j)^2.\end{aligned}$$

# Normalized Graph Laplacian

Two different normalization methods are popular, including:

- ▶ Symmetric normalization:

$$L_s = D^{-\frac{1}{2}} L D^{-\frac{1}{2}} = I - D^{-\frac{1}{2}} W D^{-\frac{1}{2}}.$$

- ▶ Normalization related to random walks:

$$L_{rw} = D^{-1} L = I - D^{-1} W.$$

## Remarks

1. For every vector  $x \in \mathbb{R}^n$ , we have

$$x^T L_s x = \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n W_{ij} \left( \frac{x_i}{\sqrt{d_i}} - \frac{x_j}{\sqrt{d_j}} \right)^2.$$

2.  $L_{sym}$  and  $L_{rw}$  are positive semidefinite and have  $n$  nonnegative real-valued eigenvalues,  $\lambda_1 \geq \dots \geq \lambda_n = 0$ .
3.  $\lambda$  is an eigenvalue of  $L_{rw}$  with eigenvector  $u$  if and only if  $\lambda$  is an eigenvalue of  $L_s$  with eigenvector  $D^{1/2}u$ .
4.  $\lambda$  is an eigenvalue of  $L_{rw}$  with eigenvector  $u$  if and only if  $\lambda$  and  $u$  solves the generalized eigenvalue problem  $Lu = \lambda Du$ .
5. 0 is an eigenvalue of  $L_{rw}$  with the constant one vector  $\mathbf{1}$  as eigenvector. 0 is an eigenvalue of  $L_s$  with eigenvector  $D^{1/2}\mathbf{1}$ .

# Unnormalized Spectral Clustering

1. Construct a neighborhood graph with corresponding adjacency matrix  $W$ .
2. Compute the unnormalized graph Laplacian  $L = D - W$ .
3. Find the  $k$  smallest eigenvectors of  $L$  and form the matrix  $U = [u_1 \cdots u_k] \in \mathbb{R}^{n \times k}$ .
4. Treating each row of  $U$  as a point in  $\mathbb{R}^k$ , cluster them into  $k$  groups using  $k$ -means algorithm.
5. Assign  $v_i$  to cluster  $j$  if and only if row  $i$  of  $U$  is assigned to cluster  $j$ .

# Normalized Spectral Clustering: Shi-Malik

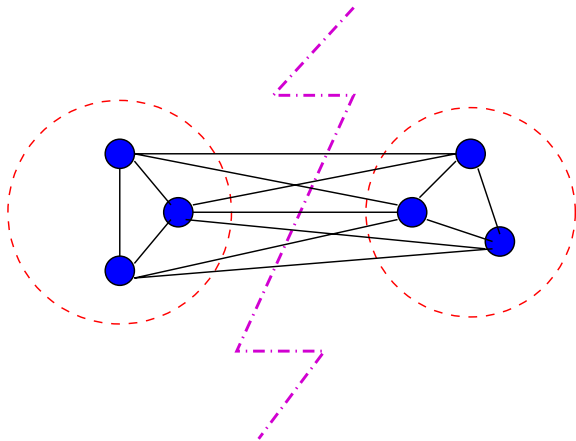
1. Construct a neighborhood graph with corresponding adjacency matrix  $W$ .
2. Compute the unnormalized graph Laplacian  $L = D - W$ .
3. Find the  $k$  smallest generalized eigenvectors  $u_1, \dots, u_k$  of the problem  $Lu = \lambda Du$  and form the matrix  $U = [u_1 \cdots u_k] \in \mathbb{R}^{n \times k}$ .
4. Treating each row of  $U$  as a point in  $\mathbb{R}^k$ , cluster them into  $k$  groups using  $k$ -means algorithm.
5. Assign  $v_i$  to cluster  $j$  if and only if row  $i$  of  $U$  is assigned to cluster  $j$ .

# Normalized Spectral Clustering: Ng-Jordan-Weiss

1. Construct a neighborhood graph with corresponding adjacency matrix  $W$ .
2. Compute the normalized graph Laplacian  $L_s = D^{-1/2}LD^{-1/2}$ .
3. Find the  $k$  smallest eigenvectors  $u_1, \dots, u_k$  of  $L_s$  and form the matrix  $U = [u_1 \cdots u_k] \in \mathbb{R}^{n \times k}$ .
4. Form the matrix  $\tilde{U}$  from  $U$  by re-normalizing each row of  $U$  to have unit norm, i.e.,  $\tilde{U}_{ij} = U_{ij}/(\sum_j U_{ij})^{1/2}$ .
5. Treating each row of  $\tilde{U}$  as a point in  $\mathbb{R}^k$ , cluster them into  $k$  groups using  $k$ -means algorithm.
6. Assign  $v_i$  to cluster  $j$  if and only if row  $i$  of  $\tilde{U}$  is assigned to cluster  $j$ .



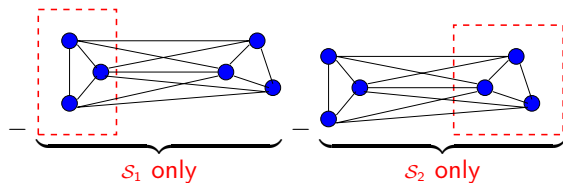
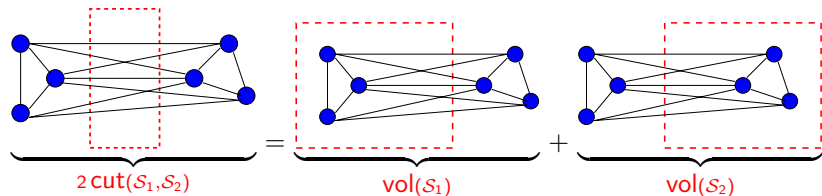
# Pictorial Illustration of Graph Partitioning



# Graph Partitioning: Bipartitioning

- ▶ Consider a connected graph  $\mathcal{G}(\mathcal{V}, \mathcal{E})$  where  $\mathcal{V} = \{v_1, \dots, v_n\}$  and  $\mathcal{E}$  denote a set of vertices and a set of edges, respectively, with pairwise similarity values being assigned as edge weights.
- ▶ Graph bipartitioning involves taking the set  $\mathcal{V}$  apart into two coherent groups,  $\mathcal{S}_1$  and  $\mathcal{S}_2$ , satisfying  $\mathcal{V} = \mathcal{S}_1 \cup \mathcal{S}_2$ , ( $|\mathcal{V}| = n$ ), and  $\mathcal{S}_1 \cap \mathcal{S}_2 = \emptyset$ , by simply cutting edges connecting the two parts
- ▶ **Adjacency matrix (similarity, proximity, affinity matrix):**  
 $W = [W_{ij}] \in \mathbb{R}^{n \times n}$ .
- ▶ **Degree of nodes:**  $d_i = \sum_j W_{ij}$ .
- ▶ **Volume:**  $\text{vol}(\mathcal{S}_1) = d_{\mathcal{S}_1} = \sum_{i \in \mathcal{S}_1} d_i$ .

# Pictorial Illustration: Cut and Volume



# Graph Partitioning

The task is to find  $k$  disjoint sets,  $\mathcal{S}_1, \dots, \mathcal{S}_k$ , given  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ , where  $\mathcal{S}_1 \cap \dots \cap \mathcal{S}_k = \phi$  and  $\mathcal{S}_1 \cup \dots \cup \mathcal{S}_k = \mathcal{V}$  such that a certain cut criterion is minimized.

1. **Bipartitioning:**  $\text{cut}(\mathcal{S}_1, \mathcal{S}_2) = \sum_{i \in \mathcal{S}_1} \sum_{j \in \mathcal{S}_2} W_{ij}$ .
2. **Multiway partitioning:**  $\text{cut}(\mathcal{S}_1, \dots, \mathcal{S}_k) = \sum_{i=1}^k \text{cut}(\mathcal{S}_i, \bar{\mathcal{S}}_i)$ .
3. **Ratio cut:**  $\text{Rcut}(\mathcal{S}_1, \dots, \mathcal{S}_k) = \sum_{i=1}^k \frac{\text{cut}(\mathcal{S}_i, \bar{\mathcal{S}}_i)}{|\mathcal{S}_i|}$ .
4. **Normalized cut:**  $\text{Ncut}(\mathcal{S}_1, \dots, \mathcal{S}_k) = \sum_{i=1}^k \frac{\text{cut}(\mathcal{S}_i, \bar{\mathcal{S}}_i)}{\text{vol}(\mathcal{S}_i)}$ .

## Cut: Bipartitioning

The degree of dissimilarity between  $\mathcal{S}_1$  and  $\mathcal{S}_2$  can be computed by the total weights of edges that have been removed.

$$\begin{aligned}\text{Cut}(\mathcal{S}_1, \mathcal{S}_2) &= \sum_{i \in \mathcal{S}_1} \sum_{j \in \mathcal{S}_2} W_{ij} \\ &= \frac{1}{2} \left\{ \sum_{i \in \mathcal{S}_1} d_i + \sum_{j \in \mathcal{S}_2} d_j - \sum_{i \in \mathcal{S}_1} \sum_{j \in \mathcal{S}_1} W_{ij} - \sum_{i \in \mathcal{S}_2} \sum_{j \in \mathcal{S}_2} W_{ij} \right\} \\ &= \frac{1}{4} \left\{ (q_1 - q_2)^\top L (q_1 - q_2) \right\},\end{aligned}$$

where  $q_j = [q_{1j} \cdots q_{nj}]^\top \in \mathbb{R}^n$  is the indicator vector which represents partitions,

$$q_{ij} = \begin{cases} 1, & \text{if } i \in \mathcal{S}_j \\ 0, & \text{if } i \notin \mathcal{S}_j \end{cases}, \quad \text{for } i = 1, \dots, n \text{ and } j = 1, 2.$$

Note that  $q_1$  and  $q_2$  are orthogonal, i.e.,  $q_1^\top q_2 = 0$ .

Introducing bipolar indicator vector,  $x = q_1 - q_2 \in \{+1, -1\}^n$ , the cut criterion is simplified as

$$\text{Cut}(S_1, S_2) = \frac{1}{4} x^\top L x.$$

The balanced cut involves the following combinatorial optimization problem

$$\begin{aligned} \arg \min_x x^\top L x \\ \text{subject to } \mathbf{1}^\top x = 0, \quad x \in \{1, -1\}. \end{aligned}$$

Dropping the integer constraints ([spectral relaxation](#)), leads to the symmetric eigenvalue problem. The [second smallest](#) eigenvector of  $L$  corresponds to the solution, since the smallest eigenvalue of  $L$  is 0 and its associated eigenvector is  $\mathbf{1}$ . The second smallest eigenvector is known as [Fiedler vector](#).

## Suggested Further Readings

1. P. K. Chan, M. D. F. Schlag, and J. Y. Zien, "Spectral k-way ratio-cut partitioning and clustering," IEEE Trans. CAD of Integrated Circuits and Systems, 1994.
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3. Y. Weiss, "Segmentation using eigenvectors: A unifying view," ICCV-1999.
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6. A. Ng, M. Jordan, and Y. Weiss, "On spectral clustering: Analysis and an algorithm," NIPS-2001.
7. U. von Luxburg, "A tutorial on spectral clustering," MPI for Biological Cybernetics, TR-149, 2006.